

CNC Router Inverter Alarm Condition

1. Bus bar under voltage fault protection (E001)

① Whether there is an instantaneous power failure ?

If yes, please Inverter reset.

If no, please detecting ② whether the inverter input voltage value within the specifications ?

If no, please adjust the power supply or exclude the external power supply circuit fault.

If yes, please measure the DC bus voltage ③ whether is normal ?

If the DC bus voltage is not normal, please check ④ whether the rectifier bridge and the buffer resistance is normal ?

If no, please replace damaged bridge rectifier and buffer resistor.

If yes, please check ⑤ whether the drive board is normal ?

If no, please replace the driver board.

If yes, please check ⑥ whether the main control board is normal ?

If no, please replace the control board.

As for ③ whether, if the DC bus voltage is normal, you can directly check ⑤ whether the drive board is normal.

If no, please replace the driver board.

If yes, please check ⑥ whether the main control board is normal.

If no, please replace the control board.

2. Acceleration over voltage protection (E002)

① Whether input voltage is too high ?

If yes, please set the voltage to normal range.

If no, ② whether there are external to run motor in the process of speeding up ?

If yes, please Cancel the external power or install braking resistor.

If no, ③ whether acceleration time is too short ?

If yes, Increase the acceleration time.

If no, ④ Whether equipped with a brake unit and brake resistor?

If no, Installation of brake unit and resistor.

If yes, Seek technical support.

3. Constant speed over voltage protection (E003)

① Whether input voltage is too high ?

If yes, Set the voltage to normal range.

If no, ② whether there are external to run motor in the process of speeding up ?

If yes, please Cancel the external power or install braking resistor.

If no, Seek technical support.

4. Acceleration over-current protection (E004)

Check ① whether the inverter output circuit or short circuit to ground ?

If yes, Exclude peripheral fault.

If no, ② Whether the motor parameters self-learning?

If no, the motor parameters self-learning.

If yes, ③ whether acceleration time is too short?

If yes, Increase the acceleration time.

If no, ④ whether Manual torque boost or V / F curve is appropriate?

If no, Adjust the manual torque boost or V / F curve.

If yes, ⑤ Whether the voltage is low ?

If yes, Set the voltage to normal range.

If no, ⑥ Whether the rotating click to start ?

If yes, Select the speed tracking restart or wait until the motor stops.

If no, ⑦ whether is there a load on the acceleration process?

If yes, Cancel sudden load.

If no, Selection of the inverter is too small.

5. Deceleration overcurrent protection (E005)

Check ① whether the inverter output circuit or short circuit to ground ?

If yes, Exclude peripheral fault.

If no, ② Whether the motor parameters self-learning?

If no, the motor parameters self-learning.

If yes, ③ whether acceleration time is too short?

If yes, Increase the acceleration time.

If no, ④ Whether the voltage is low ?

If yes, Set the voltage to normal range.

If no, ⑤ whether is there a load on the acceleration process?

If yes, Cancel sudden load.

If no, ④ Whether equipped with a brake unit and brake resistor?

If no, Installation of brake unit and brake resistor.

If yes, Seek technical support.

6. Constant speed overcurrent protection (E006)

Check ① whether inverter output circuit is for shorts or leakage current?

If yes, Exclude peripheral fault, if the line is too long then add the output of the reactor.

If no, ② Whether the motor parameters self-learning?

If no, the motor parameters self-learning.

If yes, ③ whether is there a sudden load in operation?

If yes, Cancel sudden load.

If no, ④ Whether the converter load can be reduced?

If yes, Lighten the load.

If no, Inverter type is too small.